Online class # 07

Date: 01/08/2021

Chapter 05 (Vector Integration)

Time: 0930 - 1030

Video: https://youtu.be/CvpNijhqtOo

Vector Integration

Chapter 5



= N1 +y) + Zir f (idn+j dy)

ORDINARY INTEGRALS OF VECTORS. Let $\mathbf{R}(u) = R_1(u)\mathbf{i} + R_2(u)\mathbf{j} + R_3(u)\mathbf{k}$ be a vector depending on a single scalar variable u, where $R_1(u)$, $R_2(u)$, $R_3(u)$ are supposed continuous in a specified interval. Then

$$\int \mathbf{R}(u) du = \mathbf{i} \int R_1(u) du + \mathbf{j} \int R_2(u) du + \mathbf{k} \int R_3(u) du$$

is called an indefinite integral of $\mathbf{R}(u)$. If there exists a vector $\mathbf{S}(u)$ such that $\mathbf{R}(u) = \frac{d}{du}(\mathbf{S}(u))$, then

$$\int \mathbf{R}(u) du = \int \frac{d}{du} (\mathbf{S}(u)) du = \mathbf{S}(u) + \mathbf{c}$$

where c is an arbitrary constant vector independent of u. The definite integral between limits u=a and u=b can in such case be written

$$\int_a^b \mathbf{R}(u) du = \int_a^b \frac{d}{du} (\mathbf{S}(u)) du = \mathbf{S}(u) + \mathbf{c} \Big|_a^b = \mathbf{S}(b) - \mathbf{S}(a)$$

This integral can also be defined as a limit of a sum in a manner analogous to that of elementary integral calculus.

LINE INTEGRALS. Let r(u) = x(u)i + y(u)j + z(u)k, where r(u) is the position vector of (x,y,z), define a curve C joining points P_1 and P_2 , where $u = u_1$ and $u = u_2$ respectively.

We assume that C is composed of a finite number of curves for each of which $\mathbf{r}(u)$ has a continuous derivative. Let $\mathbf{A}(x,y,z) = A_1\mathbf{i} + A_2\mathbf{j} + A_3\mathbf{k}$ be a vector function of position defined and continuous along C. Then the integral of the tangential component of \mathbf{A} along C from P_1 to P_2 , written as

$$\int_{P_1}^{P_2} \mathbf{A} \cdot d\mathbf{r} = \int_{C} \mathbf{A} \cdot d\mathbf{r} = \int_{C} A_1 \, dx + A_2 \, dy + A_3 \, dz$$

is an example of a line integral. If A is the force F on a particle moving along C, this line integral represents the work done by the force. If C is a closed curve (which we shall suppose is a simple closed curve, i.e. a curve which does not intersect itself anywhere) the integral around C is often denoted by

$$\oint \mathbf{A} \cdot d\mathbf{r} = \oint A_1 dx + A_2 dy + A_3 dz$$

In aerodynamics and fluid mechanics this integral is called the circulation of A about C, where A represents the velocity of a fluid.

THEOREM. If $A = \nabla \phi$ everywhere in a region R of space, defined by $a_1 \le x \le a_2$, $b_1 \le y \le b_2$, $c_1 \le z \le c_2$, where $\phi(x,y,z)$ is single-valued and has continuous derivatives in R, then

1.
$$\int_{P_1}^{P_2} \mathbf{A} \cdot d\mathbf{r}$$
 is independent of the path C in R joining P_1 and P_2 .

2.
$$\oint_C \mathbf{A} \cdot d\mathbf{r} = 0$$
 around any closed curve C in R .

In such case A is called a conservative vector field and ϕ is its scalar potential.

A vector field **A** is conservative if and only if $\nabla \times \mathbf{A} = \mathbf{0}$, or equivalently $\mathbf{A} = \nabla \phi$. In such case $\mathbf{A} \cdot d\mathbf{r} = A_1 dx + A_2 dy + A_3 dz = d\phi$, an exact differential. See Problems 10-14.

SURFACE INTEGRALS. Let S be a two-sided surface, such as shown in the figure below. Let one side of S be considered arbitrarily as the positive side (if S is a closed surface this is taken as the outer side). A unit normal \mathbf{n} to any point of the positive side of S is called a *positive* or *outward drawn* unit normal.

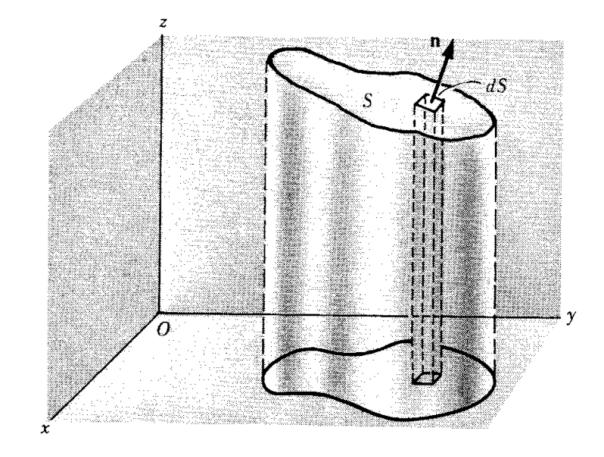
Associate with the differential of surface area dS a vector $d\mathbf{S}$ whose magnitude is dS and whose direction is that of \mathbf{n} . Then $d\mathbf{S} = \mathbf{n} \ dS$. The integral

$$\iint_{S} \mathbf{A} \cdot d\mathbf{S} = \iint_{S} \mathbf{A} \cdot \mathbf{n} \ dS$$

is an example of a surface integral called the flux of **A** over S. Other surface integrals are

$$\iint_{S} \phi \ dS, \quad \iint_{S} \phi \ \mathbf{n} \ dS, \quad \iint_{S} \mathbf{A} \times d\mathbf{S}$$

where ϕ is a scalar function. Such integrals can be defined in terms of limits of sums as in elementary calculus (see Problem 17).



VOLUME INTEGRALS. Consider a closed surface in space enclosing a volume V. Then

$$\iiint\limits_V \mathbf{A} \ dV \quad \text{ and } \quad \iiint\limits_V \phi \ dV$$

are examples of volume integrals or space integrals as they are sometimes called. For evaluation of such integrals, see the Solved Problems.



1. If
$$\mathbf{R}(u) = (u - u^2)\mathbf{i} + 2u^3\mathbf{j} - 3\mathbf{k}$$
, find (a) $\int_1^2 \mathbf{R}(u) du$ and (b) $\int_1^2 \mathbf{R}(u) du$.

$$\int P(u)du = \int S(u-u)i + \frac{3i-34}{3}du$$

$$\int Udu - i \int Udu + 2i \int Udu$$

1. If
$$\mathbf{R}(u) = (u - u^2)\mathbf{i} + 2u^3\mathbf{j} - 3\mathbf{k}$$
, find (a) $\int \mathbf{R}(u) du$ and (b) $\int_1^2 \mathbf{R}(u) du$.

$$\int_{1}^{2} p(w) du = \left(\frac{u^{2}}{2} - \frac{u^{3}}{3} \right) i + \frac{u^{4}}{2} i - 344$$

2. The acceleration of a particle at any time $t \ge 0$ is given by

$$\mathbf{a} = \frac{d\mathbf{v}}{dt} = 12\cos 2t \,\mathbf{i} - 8\sin 2t \,\mathbf{j} + 16t \,\mathbf{k}$$

If the velocity v and displacement r are zero at t=0, find v and r at any time.

$$\frac{1}{\sqrt{100}} = \frac{1}{\sqrt{100}} + \frac{1}{\sqrt{100}} = \frac{1}$$

 $\bar{v}(t) = i6 \sin 2t + i(4 \cos 2t - 4) + k8t$ $\bar{v}(t) = i6 \sin 2t + i(4 \sin 2t - 4t) + k8t$ $\bar{v}(t) = i6 \sin 2t + i(4 \sin 2t - 4t) + k8t$

7(4) = (3-36024)i+(25in2t-4)+ $83t^{2}$

3. Evaluate
$$\int \mathbf{A} \times \frac{d^2 \mathbf{A}}{dt^2} dt$$
.

$$\frac{d}{dt}(\mathbf{A} \times \frac{d\mathbf{A}}{dt}) = \mathbf{A} \times \frac{d^2\mathbf{A}}{dt^2} + \frac{d\mathbf{A}}{dt} \times \frac{d\mathbf{A}}{dt} = \mathbf{A} \times \frac{d^2\mathbf{A}}{dt^2}$$

Integrating,
$$\int \mathbf{A} \times \frac{d^2 \mathbf{A}}{dt^2} dt = \int \frac{d}{dt} (\mathbf{A} \times \frac{d\mathbf{A}}{dt}) dt = \mathbf{A} \times \frac{d\mathbf{A}}{dt} + \mathbf{c}.$$

- 6. If $\mathbf{A} = (3x^2 + 6y)\mathbf{i} 14yz\mathbf{j} + 20xz^2\mathbf{k}$, evaluate $\int_C \mathbf{A} \cdot d\mathbf{r}$ from (0,0,0) to (1,1,1) along the following paths C:
 - $(a) x = t, (y = t^2), z = t^3.$
 - (b) the straight lines from (0,0,0) to (1,0,0), then to (1,1,0), and then to (1,1,1).
 - (c) the straight line joining (0,0,0) and (1,1,1).

