

Quantum Mechanics I

PHY 3103

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Angular Momentum



Angular momentum

In classical physics the angular momentum of a particle with momentum \mathbf{p} and position \mathbf{r} is defined by

$$\mathbf{L} = \mathbf{r} \times \mathbf{p}.$$

Hence the components of $\mathbf{L} = (L_x, L_y, L_z)$ are given by

$$L_x = yp_z - zp_y,$$

$$L_y = zp_x - xp_z,$$

$$L_z = xp_y - yp_x.$$



Angular momentum operator

The angular momentum operator $\hat{\mathbf{L}} = (\hat{L}_x, \hat{L}_y, \hat{L}_z)$ can be obtained by replacing \mathbf{r} and \mathbf{p} by the corresponding operators in the position representation:

$$\hat{L}_x = \hat{y}\hat{p}_z - \hat{z}\hat{p}_y = -i\hbar \left(y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y} \right)$$
$$\hat{L}_y = \hat{z}\hat{p}_x - \hat{x}\hat{p}_z = -i\hbar \left(z \frac{\partial}{\partial x} - x \frac{\partial}{\partial z} \right)$$
$$\hat{L}_z = \hat{x}\hat{p}_y - \hat{y}\hat{p}_x = -i\hbar \left(x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} \right)$$



Hermiticity of angular momentum operator

$$\begin{aligned}(\hat{L}_x)^\dagger &= (\hat{y}\hat{p}_z - \hat{z}\hat{p}_y)^\dagger \\ &= (\hat{y}\hat{p}_z)^\dagger - (\hat{z}\hat{p}_y)^\dagger \\ &= (\hat{p}_z)^\dagger(\hat{y})^\dagger - (\hat{p}_y)^\dagger(\hat{z})^\dagger \\ &= \hat{p}_z\hat{y} - \hat{p}_y\hat{z} \\ &= \hat{y}\hat{p}_z - \hat{z}\hat{p}_y \\ &= \hat{L}_x\end{aligned}$$

$$(\hat{A}\hat{B})^\dagger = \hat{B}^\dagger\hat{A}^\dagger$$

$$\hat{L}_x^\dagger = \hat{L}_x, \quad \hat{L}_y^\dagger = \hat{L}_y, \quad \hat{L}_z^\dagger = \hat{L}_z.$$



Commutation relations

$$\begin{aligned}[\hat{L}_x, \hat{L}_y] &= [\hat{y}\hat{p}_z - \hat{z}\hat{p}_y, \hat{z}\hat{p}_x - \hat{x}\hat{p}_z] \\&= [\hat{y}\hat{p}_z, \hat{z}\hat{p}_x] - [\hat{y}\hat{p}_z, \hat{x}\hat{p}_z] - [\hat{z}\hat{p}_y, \hat{z}\hat{p}_x] + [\hat{z}\hat{p}_y, \hat{x}\hat{p}_z] \\&= [\hat{y}\hat{p}_z, \hat{z}\hat{p}_x] + [\hat{z}\hat{p}_y, \hat{x}\hat{p}_z] \\&= \hat{y}[\hat{p}_z, \hat{z}]\hat{p}_x + \hat{x}[\hat{z}, \hat{p}_z]\hat{p}_y \\&= \hat{y}(-i\hbar)\hat{p}_x + \hat{x}(i\hbar)\hat{p}_y \\&= i\hbar(\hat{x}\hat{p}_y - \hat{y}\hat{p}_x) \\&= i\hbar\hat{L}_z.\end{aligned}$$



Commutation relations

Orbital angular momentum

$$[\hat{L}_x, \hat{L}_y] = i\hbar\hat{L}_z, \quad [\hat{L}_y, \hat{L}_z] = i\hbar\hat{L}_x, \quad [\hat{L}_z, \hat{L}_x] = i\hbar\hat{L}_y.$$

Spin angular momentum

$$[\hat{S}_x, \hat{S}_y] = i\hbar\hat{S}_z, \quad [\hat{S}_y, \hat{S}_z] = i\hbar\hat{S}_x, \quad [\hat{S}_z, \hat{S}_x] = i\hbar\hat{S}_y.$$



Simultaneous eigenstates of angular momentum

$$[\hat{L}_x, \hat{L}_y] = i\hbar\hat{L}_z, \quad [\hat{L}_y, \hat{L}_z] = i\hbar\hat{L}_x, \quad [\hat{L}_z, \hat{L}_x] = i\hbar\hat{L}_y.$$

$$\hat{L}_x\psi_0 = \lambda_x\psi_0$$

$$\hat{L}_y\psi_0 = \lambda_y\psi_0$$

$$\hat{L}_z\psi_0 = \lambda_z\psi_0$$

$$\begin{aligned} i\hbar\hat{L}_z\psi_0 &= [\hat{L}_x, \hat{L}_y]\psi_0 \\ &= \hat{L}_x\hat{L}_y\psi_0 - \hat{L}_y\hat{L}_x\psi_0 \\ &= \hat{L}_x\lambda_y\psi_0 - \hat{L}_y\lambda_x\psi_0 \\ &= (\lambda_x\lambda_y - \lambda_y\lambda_x)\psi_0 \\ &= 0 \end{aligned}$$

$$\hat{L}_x\psi_0 = \hat{L}_y\psi_0 = \hat{L}_z\psi_0 = 0.$$

$$\lambda_z = 0.$$



Simultaneous eigenstates of angular momentum

$$\hat{\mathbf{L}}^2 = \hat{L}_x^2 + \hat{L}_y^2 + \hat{L}_z^2$$

$$\begin{aligned} [\hat{L}_z, \hat{\mathbf{L}}^2] &= [\hat{L}_z, \hat{L}_x \hat{L}_x + \hat{L}_y \hat{L}_y + \hat{L}_z \hat{L}_z] \\ &= [\hat{L}_z, \hat{L}_x \hat{L}_x + \hat{L}_y \hat{L}_y] \\ &= [\hat{L}_z, \hat{L}_x] \hat{L}_x + \hat{L}_x [\hat{L}_z, \hat{L}_x] + [\hat{L}_z, \hat{L}_y] \hat{L}_y + \hat{L}_y [\hat{L}_z, \hat{L}_y] \\ &= i\hbar \hat{L}_y \hat{L}_x + i\hbar \hat{L}_x \hat{L}_y - i\hbar \hat{L}_x \hat{L}_y - i\hbar \hat{L}_y \hat{L}_x \\ &= 0. \end{aligned}$$



Angular momentum in spherical coordinates

$$x = r \sin \theta \cos \phi,$$

$$r = \sqrt{x^2 + y^2 + z^2},$$

$$y = r \sin \theta \sin \phi,$$

$$\theta = \cos^{-1} \left(\frac{z}{r} \right),$$

$$z = r \cos \theta,$$

$$\phi = \tan^{-1} \left(\frac{y}{x} \right).$$

$$\hat{L}_z = \hat{x}\hat{p}_y - \hat{y}\hat{p}_x = -i\hbar \left(x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x} \right)$$



Angular momentum in spherical coordinates

$$\begin{aligned}\frac{\partial}{\partial \phi} &= \frac{\partial x}{\partial \phi} \frac{\partial}{\partial x} + \frac{\partial y}{\partial \phi} \frac{\partial}{\partial y} + \frac{\partial z}{\partial \phi} \frac{\partial}{\partial z} \\ &= -y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y} + 0 \\ &= x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x},\end{aligned}$$

$$\hat{L}_z = -i\hbar \frac{\partial}{\partial \phi}$$



Angular momentum in spherical coordinates

$$\hat{L}_x = i\hbar \left(\sin \phi \frac{\partial}{\partial \theta} + \cot \theta \cos \phi \frac{\partial}{\partial \phi} \right),$$

$$\hat{L}_y = i\hbar \left(-\cos \phi \frac{\partial}{\partial \theta} + \cot \theta \sin \phi \frac{\partial}{\partial \phi} \right)$$

$$\hat{L}_z = -i\hbar \frac{\partial}{\partial \phi}.$$

$$\hat{\mathbf{L}}^2 = -\hbar^2 \left[\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right].$$



Eigenvalues of angular momentum

$$\hat{L}_z \psi_{lm}(\theta, \phi) = \hbar m \psi_{lm}(\theta, \phi), \quad m \in \mathbb{R}$$

$$\hat{\mathbf{L}}^2 \psi_{lm}(\theta, \phi) = \hbar^2 l(l+1) \psi_{lm}(\theta, \phi), \quad l \in \mathbb{R}.$$

$$\begin{aligned} (\psi, \hat{\mathbf{L}}^2 \psi) &= (\psi, \hat{L}_x^2 \psi) + (\psi, \hat{L}_y^2 \psi) + (\psi, \hat{L}_z^2 \psi) \\ &= (\hat{L}_x \psi, \hat{L}_x \psi) + (\hat{L}_y \psi, \hat{L}_y \psi) + (\hat{L}_z \psi, \hat{L}_z \psi) \geq 0 \end{aligned}$$



Eigenvalues of angular momentum

$$\hat{L}_z = -i\hbar \frac{\partial}{\partial \phi}$$

$$-i\hbar \frac{\partial \psi_{lm}}{\partial \phi} = \hbar m \psi_{lm}$$

$$\frac{\partial \psi_{lm}}{\partial \phi} = im \psi_{lm}$$

$$\psi_{lm}(\theta, \phi) = e^{im\phi} P_l^m(\theta)$$

$$\psi_{lm}(\theta, \phi + 2\pi) = \psi_{lm}(\theta, \phi)$$

$$e^{im(\phi+2\pi)} = e^{im\phi}$$

$$e^{i2\pi m} = 1$$

$$m \in \mathbb{Z}$$



Eigenvalues of angular momentum

$$\hat{L}_z \psi_{lm}(\theta, \phi) = \hbar m \psi_{lm}(\theta, \phi),$$

$$\hat{\mathbf{L}}^2 \psi_{lm}(\theta, \phi) = \hbar^2 l(l+1) \psi_{lm}(\theta, \phi),$$

$$l = 0, 1, 2, 3, \dots$$

$$m \in \mathbb{Z}$$

$$-l \leq m \leq l.$$



Eigenfunctions of angular momentum

Spherical harmonics

$$Y_{lm}(\theta, \phi) = (-1)^m \sqrt{\left(\frac{2l+1}{4\pi}\right) \frac{(l-m)!}{(l+m)!}} P_l^m(\cos \theta) e^{im\phi}, \quad (m \geq 0).$$

Here $P_l^m(\cos \theta)$ is the associated Legendre functions. $m < 0$, we use

$$Y_{l,m}(\theta, \phi) = (-1)^m [Y_{l,-m}(\theta, \phi)]^*.$$

$$\int_0^{2\pi} d\phi \int_0^\pi d\theta \sin \theta Y_{l'm'}^*(\theta, \phi) Y_{lm}(\theta, \phi) = (Y_{l'm'}^*, Y_{lm}) = \delta_{l'l} \delta_{m'm}.$$



Eigenfunctions of angular momentum

Spherical harmonics

$$Y_{lm}(\theta, \phi) = (-1)^m \sqrt{\left(\frac{2l+1}{4\pi}\right) \frac{(l-m)!}{(l+m)!}} P_l^m(\cos \theta) e^{im\phi}, \quad (m \geq 0).$$

$$\hat{L}_z Y_{lm} = \hbar m Y_{lm},$$

$$\hat{L}^2 Y_{lm} = \hbar^2 l(l+1) Y_{lm},$$

$$m \in \mathbb{Z}$$

$$l = 0, 1, 2, 3, \dots$$

$$-l \leq m \leq l.$$



Eigenfunctions of angular momentum

$$Y_{lm}(\theta, \varphi)$$

$$Y_{00}(\theta, \varphi) = \frac{1}{\sqrt{4\pi}}$$

$$Y_{10}(\theta, \varphi) = \sqrt{\frac{3}{4\pi}} \cos \theta$$

$$Y_{1,\pm 1}(\theta, \varphi) = \mp \sqrt{\frac{3}{8\pi}} e^{\pm i\varphi} \sin \theta$$

$$Y_{20}(\theta, \varphi) = \sqrt{\frac{5}{16\pi}} (3 \cos^2 \theta - 1)$$

$$Y_{2,\pm 1}(\theta, \varphi) = \mp \sqrt{\frac{15}{8\pi}} e^{\pm i\varphi} \sin \theta \cos \theta$$

$$Y_{2,\pm 2}(\theta, \varphi) = \sqrt{\frac{15}{32\pi}} e^{\pm 2i\varphi} \sin^2 \theta$$

$$Y_{lm}(x, y, z)$$

$$Y_{00}(x, y, z) = \frac{1}{\sqrt{4\pi}}$$

$$Y_{10}(x, y, z) = \sqrt{\frac{3}{4\pi}} \frac{z}{r}$$

$$Y_{1,\pm 1}(x, y, z) = \mp \sqrt{\frac{3}{8\pi}} \frac{x \pm iy}{r}$$

$$Y_{20}(x, y, z) = \sqrt{\frac{5}{16\pi}} \frac{3z^2 - r^2}{r^2}$$

$$Y_{2,\pm 1}(x, y, z) = \mp \sqrt{\frac{15}{8\pi}} \frac{(x \pm iy)z}{r^2}$$

$$Y_{2,\pm 2}(x, y, z) = \sqrt{\frac{15}{32\pi}} \frac{x^2 - y^2 \pm 2ixy}{r^2}$$



Central potential

Consider a particle represented by a three-dimensional wave function $\psi(x, y, z)$ moving in a three dimensional potential $V(\mathbf{r})$. The Schrödinger equation takes the form

$$-\frac{\hbar^2}{2m} \nabla^2 \psi(\mathbf{r}) + V(\mathbf{r})\psi(\mathbf{r}) = E\psi(\mathbf{r}).$$

We have a **central potential** if $V(\mathbf{r}) = V(r)$.

In spherical coordinates, the Laplacian is

$$\nabla^2 \psi = (\nabla \cdot \nabla) \psi = \left[\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right] \psi.$$



The Schrödinger equation

$$-\frac{\hbar^2}{2m} \left[\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) + \frac{1}{r^2} \left\{ \frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right\} \right] \psi + V(r)\psi(\mathbf{r}) = E\psi(\mathbf{r})$$

$$\hat{\mathbf{L}}^2 = -\hbar^2 \left[\frac{1}{\sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial}{\partial \theta} \right) + \frac{1}{\sin^2 \theta} \frac{\partial^2}{\partial \phi^2} \right].$$

$$-\frac{\hbar^2}{2m} \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) \psi(\mathbf{r}) + \frac{\hat{\mathbf{L}}^2}{2mr^2} \psi(\mathbf{r}) + V(r)\psi(\mathbf{r}) = E\psi(\mathbf{r}).$$



Problems

Chapter 5
Angular Momentum
Quantum Mechanics
Nouredine Zettili

Example 5.1, 5.2

Problem 5.9, 5.11

Exercise 5.1 – 5.4



Problem 5.9

Consider a system which is initially in the state

$$\psi(\theta, \varphi) = \frac{1}{\sqrt{5}}Y_{1,-1}(\theta, \varphi) + \sqrt{\frac{3}{5}}Y_{10}(\theta, \varphi) + \frac{1}{\sqrt{5}}Y_{11}(\theta, \varphi).$$

- (a) Find $\langle \psi | \hat{L}_+ | \psi \rangle$.
- (b) If \hat{L}_z were measured what values will one obtain and with what probabilities?
- (c) If after measuring \hat{L}_z we find $l_z = -\hbar$, calculate the uncertainties ΔL_x and ΔL_y and their product $\Delta L_x \Delta L_y$.



Solution

$$\hat{J}_{\pm} = \hat{J}_x \pm i\hat{J}_y.$$

$$\hat{J}_x = \frac{1}{2}(\hat{J}_+ + \hat{J}_-), \quad \hat{J}_y = \frac{1}{2i}(\hat{J}_+ - \hat{J}_-);$$

$$[\hat{J}^2, \hat{J}_{\pm}] = 0, \quad [\hat{J}_+, \hat{J}_-] = 2\hbar\hat{J}_z, \quad [\hat{J}_z, \hat{J}_{\pm}] = \pm\hbar\hat{J}_{\pm}.$$

$$\hat{J}_{\pm} |j, m\rangle = \hbar\sqrt{j(j+1) - m(m \pm 1)} |j, m \pm 1\rangle$$

$$\langle j, m | \hat{J}_x | j, m \rangle = \langle j, m | \hat{J}_y | j, m \rangle = 0$$

$$\langle \hat{J}_x^2 \rangle = \langle \hat{J}_y^2 \rangle = \frac{1}{2} \left[\langle j, m | \hat{J}^2 | j, m \rangle - \langle j, m | \hat{J}_z^2 | j, m \rangle \right] = \frac{\hbar^2}{2} [j(j+1) - m^2].$$



Solution

(a) Let us use a lighter notation for $|\psi\rangle$: $|\psi\rangle = \frac{1}{\sqrt{5}} |1, -1\rangle + \sqrt{\frac{3}{5}} |1, 0\rangle + \frac{1}{\sqrt{5}} |1, 1\rangle$.

From (5.56) we can write $\hat{L}_+ |l, m\rangle = \hbar\sqrt{l(l+1) - m(m+1)} |l, m+1\rangle$; hence the only terms that survive in $\langle\psi | \hat{L}_+ | \psi\rangle$ are

$$\langle\psi | \hat{L}_+ | \psi\rangle = \frac{\sqrt{3}}{5} \langle 1, 0 | \hat{L}_+ | 1, -1\rangle + \frac{\sqrt{3}}{5} \langle 1, 1 | \hat{L}_+ | 1, 0\rangle = \frac{2\sqrt{6}}{5} \hbar, \quad (5.275)$$

since $\langle 1, 0 | \hat{L}_+ | 1, -1\rangle = \langle 1, 1 | \hat{L}_+ | 1, 0\rangle = \sqrt{2}\hbar$.



Solution



(b) If \hat{L}_z were measured, we will find three values $l_z = -\hbar, 0,$ and \hbar . The probability of finding the value $l_z = -\hbar$ is

$$\begin{aligned}
 P_{-1} &= |\langle 1, -1 | \psi \rangle|^2 = \left| \frac{1}{\sqrt{5}} \langle 1, -1 | 1, -1 \rangle + \sqrt{\frac{3}{5}} \langle 1, -1 | 1, 0 \rangle + \frac{1}{\sqrt{5}} \langle 1, -1 | 1, 1 \rangle \right|^2 \\
 &= \frac{1}{5},
 \end{aligned} \tag{5.276}$$

since $\langle 1, -1 | 1, 0 \rangle = \langle 1, -1 | 1, 1 \rangle = 0$ and $\langle 1, -1 | 1, -1 \rangle = 1$. Similarly, we can verify that the probabilities of measuring $l_z = 0$ and \hbar are respectively given by

$$P_0 = |\langle 1, 0 | \psi \rangle|^2 = \left| \sqrt{\frac{3}{5}} \langle 1, 0 | 1, 0 \rangle \right|^2 = \frac{3}{5}, \tag{5.277}$$

$$P_1 = |\langle 1, 1 | \psi \rangle|^2 = \left| \sqrt{\frac{1}{5}} \langle 1, 1 | 1, 1 \rangle \right|^2 = \frac{1}{5}. \tag{5.278}$$

Solution



(c) After measuring $l_z = -\hbar$, the system will be in the eigenstate $|lm\rangle = |1, -1\rangle$, that is, $\psi(\theta, \varphi) = Y_{1,-1}(\theta, \varphi)$. We need first to calculate the expectation values of \hat{L}_x , \hat{L}_y , \hat{L}_x^2 , and \hat{L}_y^2 using $|1, -1\rangle$. Symmetry requires that $\langle 1, -1 | \hat{L}_x | 1, -1\rangle = \langle 1, -1 | \hat{L}_y | 1, -1\rangle = 0$. The expectation values of \hat{L}_x^2 and \hat{L}_y^2 are equal, as shown in (5.60); they are given by

$$\langle \hat{L}_x^2 \rangle = \langle \hat{L}_y^2 \rangle = \frac{1}{2}[\langle \hat{L}^2 \rangle - \langle \hat{L}_z^2 \rangle] = \frac{\hbar^2}{2} [l(l+1) - m^2] = \frac{\hbar^2}{2}; \quad (5.279)$$

in this relation, we have used the fact that $l = 1$ and $m = -1$. Hence

$$\Delta L_x = \sqrt{\langle \hat{L}_x^2 \rangle} = \frac{\hbar}{\sqrt{2}} = \Delta L_y, \quad (5.280)$$

and the uncertainties product $\Delta L_x \Delta L_y$ is given by

$$\Delta L_x \Delta L_y = \sqrt{\langle \hat{L}_x^2 \rangle \langle \hat{L}_y^2 \rangle} = \frac{\hbar^2}{2}. \quad (5.281)$$